AN ANALYSIS OF TWO-PERSON GAME SITUATIONS IN TERMS OF STATISTICAL LEARNING THEORY

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This study represents an extension of statistical learning theory to a class of two-person, zero-sum game situations. Because the theory has been mainly developed in connection with experiments dealing with individual learning problems, its predictive success in an experimental area involving interaction between individuals provides an additional measure of the scope of its validity. It should be emphasized that the study reported here was not conceived as providing an empirical test of the adequacy of learning theory as opposed to game theory; although we use the language of game theory to describe the study, the game characteristics of the situation were not apparent to Ss. This point is amplified below.

For the purposes of this experiment, a play of a game is a trial. On a given trial each of the two players independently makes a choice between one of two alternatives—that is, he makes one of two possible responses. After the players have indicated their choices, the outcome of the trial is announced to each player.

On all trials, the game is described by the following pay-off matrix.

<table>
<thead>
<tr>
<th></th>
<th>B1</th>
<th>B2</th>
</tr>
</thead>
<tbody>
<tr>
<td>A1</td>
<td>(a_1)</td>
<td>(a_2)</td>
</tr>
<tr>
<td>A2</td>
<td>(a_3)</td>
<td>(a_4)</td>
</tr>
</tbody>
</table>

The players are designated A and B. The responses available to A are A1 and A2; similarly, the responses available to B are B1 and B2. If A selects A1 and B selects B1 then there is a probability \(a_1\) that A is “correct” and B is “incorrect,” and a probability \(1 - a_1\) that A is “incorrect” and B is “correct.” These two joint events are exhaustive since it is required that exactly one player is correct on each trial. The outcomes of the other three response pairs are identically specified in terms of \(a_2, a_3\) and \(a_4\).

The interaction of the players is limited by two factors: (a) neither player is shown the pay-off matrix, (b) neither player is directly informed of the responses of the other player. Thus, from the standpoint of the general theory of rational behavior (4), S should not regard himself as playing a 2 X 2 game with known pay-off matrix but should view the situation as a multi-stage decision problem against an unknown opponent. However, selection of an optimal strategy in this multi-stage decision problem is far from a trivial task mathematically, and it is scarcely to be expected that any S would use such a strategy. The virtue of statistical learning theory is that it yields a quantitative prediction of how organisms actually do behave in such situations.

Our theoretical analysis of the behavior of Ss in the situation described is based on two distinct but closely related models. Since a detailed mathematical analysis of these models will be presented elsewhere, the present statement will concern only the most salient facts and omit mathematical proofs.

Linear model.—The first model is an extension of a linear model developed by Estes and Burke (6). Experimental tests of this formulation for one-person learning situations have been reported.
The basic assumption of the model is that response probability on a given trial is a linear function of the probability on the preceding trial. When a response is reinforced it is increased; the reinforcement of any other response decreases its probability.

In the present situation, where two responses are available to each S, if a response occurs and is designated as "correct," then the response is reinforced; if a response occurs and is designated as "incorrect," then the alternative response is reinforced. More specifically, let \( \alpha_r \) be the probability of response \( A_1 \) on Trial \( n \). The rules of change are:

1. if \( A_1 \) is reinforced on Trial \( n \), then \( \alpha_{n+1} = (1 - \theta_A)\alpha_n + \theta_A(1 - \alpha_i) + \theta_A(\alpha_i - a)\beta_n \\ + \theta_A(a_1 + a_2 - a - a_i)\gamma_n \\ + a\beta_n(1 - \theta_A)\alpha_n \\
2. if \( A_2 \) is reinforced on Trial \( n \), then \( \alpha_{n+1} = (1 - \theta_A)\alpha_n + \theta_A\alpha_i \alpha_n \\ + \theta_A(a_1 + a_2 - a - a_i)\gamma_n \\ + a\beta_n(1 - \theta_A)\alpha_n \\

It may be shown that \( \alpha, \beta \) and \( \gamma \), the asymptotic probabilities in the sense of Cesaro (11), exist and are independent of the initial probabilities \( \alpha_0, \beta_0, \gamma_0 \). However, in general, these asymptotic quantities depend on \( \theta_A \) and \( \theta_B \), and no simple results are obtainable for the quantities individually. On the other hand, an interesting linear relation between \( \alpha \) and \( \beta \), which is independent of \( \gamma \), \( \theta_A \) and \( \theta_B \), can be derived, namely:

\[
\left[(a_2 + a_i - a_1 - a_2) + (a_1a_2 - a_1a_i)\right]x = \left[(a_2a_3 - a_1a_3)\right]y + \frac{1}{3}(a_2 + a_i - a_1 - a_2) + a_4(a_2 - a_3)
\]

The line determined by this equation has been labeled the interaction line since the exact point on the line specifying the asymptotic probabilities \( \alpha \) and \( \beta \) is a function of both \( \theta_A \) and \( \theta_B \). It is interesting to observe that in the corresponding one-person learning situation, the interaction line degenerates to a point, while in the three-person situation an interaction surface is obtained.

**Finite Markov model.** — In this model the simplifying assumption is made that on all trials a player's response behavior is determined by a single stimulus—that is, the event associated with the onset of a trial. The \( S \) is described as being in one of two possible states: (a) if in State 1, the stimulus is conditioned to Response 1 and, in the presence of the stimulus, Response 1 will be elicited; (b) if in State 2, the stimulus is conditioned to Response 2 and, in the presence of the stimulus, Response 2 will be elicited. Thus, on any Trial \( n \), the two players are described in terms of one of the following four states: \( <1,1> \), \( <1,2> \), \( <2,1> \) and \( <2,2> \) where the first member of a couple indicates the state of Player A and the second, the state of Player B. For example, \( <2,1> \) means that Player A will make response \( A_2 \) and Player B will make response \( B_2 \). It is postulated that the change of states from one trial to the next is Markovian, and the following analysis is used to derive the transition matrix (10, 11) of the process.

When one of Player A's responses is reinforced on Trial \( n \) there is (a) a probability \( \theta_A \) that the stimulus governing Player A's response will be conditioned to the reinforced response and therefore, on Trial \( n + 1 \) Player A will make the response reinforced on Trial \( n \) and, (b) a probability \( 1 - \theta_A \) that the conditioned status of the stimulus will remain unchanged and therefore, on Trial \( n + 1 \) Player A will repeat the response made on Trial \( n \). Identical rules describe the process for Player B in terms of \( \theta_B \).

4The Markov process derived from these assumptions differs in certain respects from that which can be derived from the Estes and Burke stimulus sampling model (6). In their formulation the stimulus is conceptualized as being

\( (2,9,13) \).
For this set of assumptions and the pay-off probabilities $a_1$, $a_2$, $a_3$, and $a_4$, the transition matrix describing the learning process can be derived and is as follows:

<table>
<thead>
<tr>
<th></th>
<th>$&lt;1,1&gt;$</th>
<th>$&lt;1,2&gt;$</th>
<th>$&lt;2,1&gt;$</th>
<th>$&lt;2,2&gt;$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$&lt;1,1&gt;$</td>
<td>$a_1(\theta_A - \theta_B)$ (+(1-\theta_A)\theta_B)</td>
<td>$a_2(\theta_A - \theta_B)$ (+(1-\theta_A)\theta_B)</td>
<td>(1-a_1)(\theta_A)</td>
<td>$0$</td>
</tr>
<tr>
<td>$&lt;1,2&gt;$</td>
<td>$a_3(\theta_A - \theta_B)$ (+(1-\theta_A)\theta_B)</td>
<td>$0$</td>
<td>$0$</td>
<td>((1-a_2)\theta_B)</td>
</tr>
<tr>
<td>$&lt;2,1&gt;$</td>
<td>$(1-a_3)\theta_A$</td>
<td>$0$</td>
<td>$a_4(\theta_A - \theta_B)$ (+(1-\theta_A)\theta_B)</td>
<td>$a_2\theta_B$</td>
</tr>
<tr>
<td>$&lt;2,2&gt;$</td>
<td>$0$</td>
<td>$(1-a_4)\theta_A$</td>
<td>$a_2\theta_B$</td>
<td>((1-\theta_A)\theta_B)$</td>
</tr>
</tbody>
</table>

Rows designate the state on Trial $n$ and columns the state on Trial $n+1$. Thus \((1-a_3)\theta_A\), the entry in Row 3, Column 1, is the conditional probability of being in State $<1,1>$ on Trial $n+1$ given that the pair of $S$s was in State $<2,1>$ on Trial $n$, because:

\[
(1-a_3)\theta_A = \theta_A \theta_B (1-a_3) + \theta_A (1-\theta_B) (1-a_3) + (1-\theta_A) \theta_B \theta_A - (1-\theta_A) \theta_B (1-\theta_A) \cdot 0.
\]

From these one-stage transition probabilities an explicit solution is obtained for the Cesaro asymptotic probabilities of an $A_1$ and $B_1$ response; as in the case of the linear model these quantities are denoted as $\bar{\alpha}$ and $\bar{\beta}$, respectively. The general equations for $\bar{\alpha}$ and $\bar{\beta}$ are too lengthy to reproduce here but certain results are noteworthy. It can be shown that $\bar{\alpha}$ and $\bar{\beta}$ are related by the identical interaction line determined by Equation 1 of the linear model. For the Markov model, however, it can in addition be proved that the point on the interaction line describing a particular pair of $S$s' asymptotic behaviors is uniquely determined by the ratio of $\theta_A$ to $\theta_B$. Further, even without a knowledge of the specific values of $\theta_A$ and $\theta_B$ one can specify a fairly narrow interval on the interaction line within which $\bar{\alpha}$ and $\bar{\beta}$ must fall by taking the limits of $\bar{\alpha}$ and $\bar{\beta}$ as the ratio $\theta_A/\theta_B$ approaches zero or becomes large.

Particular cases of the theoretical analysis may be illustrated by examining predictions for the parameter values employed in this experiment. Three sets of $a_1$ values were used corresponding to three classical cases of $2 \times 2$ games in the theory of zero-sum, two-person games (12).

The first case is labeled the Mixed Group, since both players have mixed minimax strategies. The $a_1$ values are given by the pay-off matrix

\[
\begin{bmatrix}
B_1 & B_2 \\
A_1 & \frac{1}{3} & 1 \\
A_2 & \frac{1}{2} & \frac{1}{2}
\end{bmatrix}
\]

The minimax strategy for Player A is to choose $A_1$ with probability $\frac{1}{3}$, and the minimax strategy for B is to choose $B_1$ with probability $\frac{1}{2}$. In the Markov model

\[
\bar{\alpha} = .600 \quad (2)
\]

\[
\bar{\beta} = \frac{35(\theta_A/\theta_B) + 22}{50(\theta_A/\theta_B) + 40} \quad (3)
\]

Note that $\bar{\alpha}$ is independent of $\theta_A/\theta_B$. From Equation 3 one obtains as bounds on $\bar{\beta}$:

\[
.550 < \bar{\beta} < .700. \quad (4)
\]

If one assumes $\theta_A = \theta_B$, then $\bar{\beta} = .633$. For this case the interaction line is the line satisfying Equation 2.

The second case is labeled the Pure Group, since both players have pure minimax strategies. The particular values...
are given by the matrix
\[
\begin{pmatrix}
B_1 & B_2 \\
A_1 & \frac{1}{2} & 1 \\
A_2 & \frac{1}{2} & \frac{1}{2}
\end{pmatrix}
\]
Here \( a_1 = \frac{1}{2} \) is a saddle point of the matrix and from the standpoint of game theory the optimal strategy for Player A is to play \( A_1 \) with probability 1 and for B to play \( B_1 \) with probability 1. In the Markov model
\[
\alpha = .667
\]
\[
\beta = \frac{6(\theta_A/\theta_B) + 5}{9(\theta_A/\theta_B) + 9}
\]
As in the previous case, \( \alpha \) is independent of \( \theta_A/\theta_B \) and the interaction line is the line satisfying Equation 5. From Equation 6 one obtains as bounds on \( \beta \):
\[
.555 < \beta < .667.
\]
If one assumes that \( \theta_A = \theta_B \), then \( \beta = .611 \).

The third case is labeled the Sure Group since both players have sure-thing strategies (i.e., given the pay-off matrix one of the two responses available to each player is at least as good or better than the other response regardless of what his opponent does). The parameter values are given by the matrix
\[
\begin{pmatrix}
B_1 & B_2 \\
A_1 & \frac{1}{2} & \frac{1}{2} \\
A_2 & \frac{1}{2} & 1
\end{pmatrix}
\]
The sure-thing strategies for Players A and B are \( A_1 \) and \( B_1 \) respectively. In the Markov model
\[
\alpha = \frac{5(\theta_A/\theta_B) + 15}{7(\theta_A/\theta_B) + 23}
\]
\[
\beta = \frac{5(\theta_A/\theta_B) + 16}{7(\theta_A/\theta_B) + 23}
\]
and as bounds one has:
\[
.652 < \alpha < .711
\]
\[
.696 < \beta < .711.
\]
If one assumes that \( \theta_A = \theta_B \), then \( \alpha = .667 \) and \( \beta = .700 \). For this case the interaction line is determined by the equation:
\[
3\alpha = 10\beta - 5.
\]

**Method**

**Subjects.**—The Ss were 120 undergraduates obtained from introductory courses in psychology and philosophy at Stanford University. They were randomly assigned to the Mixed, Pure, and Sure Groups with the restriction that there were 20 pairs of Ss in each group.

**Apparatus.**—The Ss, run in pairs, sat at opposite ends of an 8 × 3-ft. table. Mounted vertically on the table top facing each S was a 50-in. wide by 30-in. high black panel placed 22 in. from the end of the table. The E sat between the two panels and was not visible to either S. The apparatus, as viewed from S's side, consisted of two silent operating keys mounted 8 in. apart on the table top and 12 in. from the end of the table; upon the panel, three milk-glass panel lights were mounted. One of these lights, which served as the signal for S to respond, was centered between the keys at a height of 17 in. from the table top. Each of the two remaining lights, the reinforcing signals, was at a height of 11 in. directly above one of the keys. The presentation and duration of the lights were automatically controlled. The Ss were not visible to one another and could not see each other's responses or panel lights.

**Procedure.**—The Ss were read the following instructions: "We always run Ss in pairs because this is the way the equipment has been designed and also because it is the most economical procedure. Actually, however, you are both working on two completely different and independent problems. 

"The experiment for each of you consists of a series of trials. The top center lamp on your panel will light for about 2 sec. to indicate the start of each trial. Shortly thereafter one or the other of the two lower lamps will light up. Your job is to predict on each trial which one of the two lower lamps will light and indicate your prediction by pressing the proper key. That is, if you expect the left lamp to light press the left key, if you expect the right lamp to light press the right key. On each trial press one or the other of the two keys but never both. If you are not sure which key to press then guess. 

"Be sure to indicate your choice by pressing the proper key immediately after the onset of the signal light. That is, when the signal light goes on press one or the other key down and release it. Then wait until one of the lower lights goes on. If the light above the key you pressed goes on your prediction was correct, if the light above the key opposite from the one you pressed goes on you were incorrect, and should have pressed the other key. At times
you may feel frustrated or irritated if you cannot understand what the experiment is all about. Nevertheless, continue trying to make the very best prediction you can on each trial."

For each pair of Ss, one was randomly selected as Player A and the other as Player B. Further, for each S one of the two response keys was randomly designated Response 1 and the other Response 2 with the restriction that the following possible combinations occurred equally often in each of the three experimental groups: (a) $A_1$ and $B_1$ on the right, (b) $A_1$ on the right and $B_1$ on the left, (c) $A_1$ on the left and $B_1$ on the right, and (d) $A_1$ and $B_1$ on the left.

Following the instructions, 200 trials were run in continuous sequence. For each pair of Ss sequences of reinforcing lights were generated in accordance with assigned values of $a_1$ and observed responses.

On all trials the signal light was lighted for 3.5 sec.; the time between successive signal exposures was 10 sec. The reinforcing light followed the cessation of the signal light by 1.5 sec. and remained on for 2 sec.

At the end of the session each S was asked to describe what he thought was involved in the experiment. Only one S indicated that he believed the reinforcing events depended in any way on a relationship between his responses and the other player's responses. His record and that of his partner were eliminated from the analysis and replaced by another pair.

**RESULTS AND DISCUSSION**

*Mean learning curves and asymptotic results.*—Figure 1 provides a description of behavior over all trials of the experiment. In this figure the mean proportions of $A_1$ and $B_1$ responses in successive blocks of 40 trials are given for the sequence of 200 trials. An inspection of this figure indicates that responses are fairly stable over the last 100 trials except possibly for $B_1$ responses in the Pure Group. To check the stability of response behavior for individual data, $t$'s for paired measures were computed between response proportions for the first and last halves of the final block of 60 trials. In all cases the obtained values of $t$ fall short of significance at the .05 level.

![Observed proportions of $A_1$ and $B_1$ responses in blocks of 40 trials for the three experimental groups.](image)

**TABLE 1**

<table>
<thead>
<tr>
<th></th>
<th>Response $A_1$</th>
<th>Response $B_1$</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Pred.</td>
<td>Obs.</td>
</tr>
<tr>
<td>Mixed</td>
<td>.600</td>
<td>.605</td>
</tr>
<tr>
<td>Pure</td>
<td>.657</td>
<td>.670</td>
</tr>
<tr>
<td>Sure</td>
<td>.657</td>
<td>.606</td>
</tr>
</tbody>
</table>

It appears reasonable to assume that a constant level of responding has been reached; consequently the proportions computed over the last 60 trials were used as an estimate of $\alpha$ and $\beta$. Table 1 presents the observed mean proportions of $A_1$ and $B_1$ responses in the last 60 trial block and the $SD$'s associated with these means.
Each entry is based on $N = 20$. The values predicted by the Markov model for $\theta_A = \theta_B$ are also presented.

Inspection of Table 1 indicates that predicted and observed results are extremely close for the Mixed and Pure Groups; $t$ tests of the difference between these values do not approach significance at the .05 level. For the Sure Group the difference between Player B's observed and theoretical values is also not significant; but for Player A, the difference is significant. Specifically, the observed proportion of $A_1$ responses for the Sure Group is less than predicted. Note, however, that one may relinquish the assumption that $\theta_A = \theta_B$ and, given the boundary conditions specified by Equations 10 and 11, determine for the Sure Group the point on the interaction line (see Equation 12) which is nearest the observed point. This nearest point is $\bar{a} = .652$ and $\bar{b} = .696$. For this point the difference between observed and theoretical values is not significant at the .05 level for either $A_1$ or $B_1$ responses.

*Game theory comparisons.*—It is of interest to compare observed values with the game-theoretic optimal strategies discussed earlier, for it can be reasonably maintained that even though Ss do not know the pay-off matrix, after a large number of trials they have learned enough about the situation to approach an optimal game strategy. Concerning such a conjecture, the results for the Pure and Sure Groups seem decisive: the optimal game strategies of responding $A_1$ or $B_1$ with probability 1, for Player A or B, respectively, are not even crudely approximated by the observed means. Moreover, the maximum individual value in each group of 20 Ss does not approach 1; for the Pure Group max $a$ is .80 and max $b$ is .71, while for the Sure Group max $a$ is .77 and max $b$ is .84.

The results for the Mixed Group also fail to support the hypothesis that Ss, in the long run, will approach an optimal game strategy. The observed $\bar{a}$ of .605 and $\bar{b}$ of .649 both differ significantly from their respective minimax strategies of $\frac{3}{4}$ and $\frac{1}{4}$ at beyond the .001 level.

Several questions are suggested by these comparisons with game theory that are pertinent to a theory of small groups. First, would the learning theory predictions be less applicable and the optimal game strategies more closely approximated if Ss are explicitly told that they are competing with each other? Subsequent experimental work (3) indicates that the answer to this question is probably negative. Second, would optimal game strategies be more closely approximated if Ss were run for a very large number of trials over a period of several days? What evidence there is on this question from individual learning situations (7, 8, 9) tends to support the hypothesis that the long run mean probabilities would stay close to the learning theory predictions. However, detailed experimental investigation would be worthwhile. Third, would the present experimental results be affected if Ss were paid for correct responses and penalized monetarily for incorrect responses? The models formulated in the first part of this paper are not rich enough in conceptual content to express formally possible effects of different types of re-inforcing events. Fourth, will the obvious generalization of the two models to the interaction of more than two Ss be experimentally substantiated, and how will observed response probabilities compare with various proposed "solutions" of $n$-person games?

*Adequacy of Markov model.*—Because of the relatively simple mathematical character of stationary Markov processes with a finite number of
TWO-PERSON GAME SITUATIONS

TABLE 2
Observed Transition Matrices Corresponding to the Theoretical Transition Matrix Specified by the Markov Model
(Computed over the last 100 Trials)

<table>
<thead>
<tr>
<th>States</th>
<th>Mixed Group</th>
<th>Pure Group</th>
<th>Sure Group</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt;1,1&gt;</td>
<td>.37</td>
<td>.38</td>
<td>.43</td>
</tr>
<tr>
<td>&lt;1,2&gt;</td>
<td>.22</td>
<td>.27</td>
<td>.18</td>
</tr>
<tr>
<td>&lt;2,1&gt;</td>
<td>.35</td>
<td>.30</td>
<td>.30</td>
</tr>
<tr>
<td>&lt;2,2&gt;</td>
<td>.28</td>
<td>.11</td>
<td>.06</td>
</tr>
<tr>
<td>States</td>
<td>&lt;1,1&gt;</td>
<td>&lt;1,2&gt;</td>
<td>&lt;2,1&gt;</td>
</tr>
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<td>.30</td>
<td>.30</td>
</tr>
<tr>
<td>&lt;2,2&gt;</td>
<td>.28</td>
<td>.11</td>
<td>.06</td>
</tr>
</tbody>
</table>

For experimental situations involving more than one S even the extension to a two-element stimulus model is not trivial from the standpoint of computing the simplest quantities desired—namely, asymptotic response probabilities. For example, if in the one-element model one identifies the stimulus element as the signal light, a two-element model is to identify two successive signals as the two stimuli. The Markov process derived from this assumption has, for the present experiment, 16 states.

Fortunately, without examining a specific two-stage Markov model one can ask one highly relevant question about the present data: Can the data be more adequately accounted for by a two-stage model which employs information about the S on the previous two trials as compared with a one-stage model which employs information about only one preceding trial? For this purpose the $\chi^2$ test described by Anderson and Goodman (1) was used. The null hypothesis is that $p_{ijk} = p_{jk}$ for $i = 1, \ldots, 4$ where $p_{ijk}$ is the probability of State $k$ given successively States $i$ and $j$ on the two previous trials and $p_{jk}$ is the probability of State $k$ simply given State $j$ on the preceding trial. To test this hypothesis the following sum was

$$
\sum_{i,j,k} (O_{ijk} - E_{ijk})^2 / E_{ijk}
$$
computed for aggregate group data:
\[ \chi^2 = \sum_{i,j} n_{ij}^* (\hat{\theta}_{ij} - \tilde{\theta}_{ij})^2 / \tilde{\theta}_{ij}, \]

where \( n_{ij}^* = \sum_k n_{ijk} \). If the null hypothesis is true, \( \chi^2 \) has the usual limiting distribution with \( 4(4 - 1)^2 = 36 \) df.

The obtained values of \( \chi^2 \) were 81.8 for the Mixed Group, 50.5 for the Pure Group and 52.9 for the Sure Group. For the Pure and Sure Groups the value of \( \chi^2 \) is not significant at the .05 level, for the Mixed Group it is. Independent of any specific model these results indicate that for two of the three groups the learning process is fairly well approximated by a one-stage Markov process. Moreover, it is to be noted that the significant \( \chi^2 \) for the aggregated data of the Mixed Group does not entail that individual pairs of Ss were not one-stage Markovian in their responses, for the sum (in the sense pertinent here) of several Markov processes is not necessarily a Markov process. The relatively small number of observations for a given pair of Ss ruled out a separate \( \chi^2 \) test for each pair.

If, on the other hand, one accepts the approximate one-stage Markovian character of the learning process studied in this experiment, and asks if this process is stationary in the sense that the observed transition probabilities are constant over all trials, the answer is negative. In a \( \chi^2 \) analysis (1) of the aggregate observed transition matrix for the first 100 trials compared with the last 100 trials, the difference was significant at the .01 level for all three groups. These results suggest that nonstationary, single-element models need to be explored in addition to an analysis of stationary multi-stimulus element models.

**Observed and predicted variances in the linear model.**—The close agreement between predicted and observed mean asymptotic responses suggests a check of the linear model against another measure of behavior. Specifically, we were interested in checking the variance predicted by the model against the experimental results on variability presented in Table 1. The observed SD's in this table relate to the proportions of A₁ and B₁ responses in blocks of 60 trials; comparable theoretical quantities will be designated \( \sigma(A₁) \) and \( \sigma(B₁) \), respectively.

Unfortunately direct analytical computation of \( \sigma(A₁) \) and \( \sigma(B₁) \) seems impossible. Consequently it was necessary to resort to "Monte Carlo methods" (5). The basic idea of the approach is to construct a system which follows the rules specified by the theory and then make observations on the behavior of the system. By taking a large number of such observations one obtains precise estimates of theoretical quantities. In the present case, what might be considered a hypothetical S was built by programming an I.B.M. Type 650 digital computer so that its sequence of commands corresponded to the operations specified by the linear model.

Employing this procedure, estimates of \( \sigma(A₁) \) and \( \sigma(B₁) \) were obtained for various values of \( \theta_A \) and \( \theta_B \). Results from other experiments (2, 9, 13, 14) suggested that \( \theta \) values for the present study would undoubtedly be bounded between .01 and .50. Hence, combinations of .01, .10, and .50 were used in the computation; a finer gradation of values would have been desirable but the cost of computer time made this prohibitive. The results of the Monte Carlo runs are presented in Table 3.
A comparison of Tables 1 and 3 indicates that, for all cases, the observed variability is greater than predicted by the model. Even the most favorable comparisons between observed and predicted values prove to be significantly different at the .05 level when a $\chi^2$ test of variances is employed. The finding that the linear model tends to underestimate observed variability is not surprising in view of similar results from other experiments employing linear operator models to account for individual learning data.

**Summary**

The study deals with an analysis of a zero-sum, two-person game situation in terms of statistical learning theory and game theory.

The Ss were run in pairs for 200 trials. A single play of the game is treated as a trial. On a trial each player makes a choice between one of two alternative responses; after the players have made their response, the outcome of the trial is announced. The responses available to Player A are designated $A_1$ and $A_2$; similarly, the responses available to Player B are $B_1$ and $B_2$. If Player A selects $A_1$ and Player B selects $B_1$, then there is a probability $a_1$ that Player A is "correct" and Player B is "incorrect," and a probability $1 - a_1$ that Player B is "correct" and Player A is "incorrect." The outcome of the other three response pairs is identically specified in terms of $a_2$, $a_3$, and $a_4$. The Ss were instructed to maximize the number of correct responses.

Three groups were run, each employing a different set of $a_i$ values. The selection of these values was determined by game-theoretic considerations; that is, a group had available either a sure-thing strategy, a pure minimax strategy, or a mixed minimax strategy.

Analysis of the data was in terms of two different but related stochastic models for learning and game theory. Specifically the following detailed comparisons of data and theory were made: (a) mean asymptotic response probabilities, (b) one- and two-stage transition probabilities, and (c) variances associated with asymptotic response probabilities.

**REFERENCES**


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